LOGAN BECKER

My Work for demo 2:

- Integrated the bridge from the stockfish engine to ROS, creating a python node that sends stockfish's best moves to the robot for automatic piece movement
- Used lab hours to transfer files from our repo to the available laptop in the lab and test using the robotic arm
- Helped troubleshoot issues with building the workspace on the lab laptop

My github link: https://git.las.iastate.edu/SeniorDesignComS/2025fall/402c/sd07_joseph_hoane_1/-/commits/main?author=Logan%20Becker

Further Work/ Live Work:

- Improve model accuracy for better piece detection (might need more and better data collection)
- **Get ready for a pick and place demo with our client (no stockfish just a set pick and place movement)**

Issues/Question:

- Half semester class started and conflicts with Wednesday lab times